

2018 秋季本科时间序列  
第六次作业答案

2018 年 12 月 4 日

1. (a)

$$\boldsymbol{\theta} = \begin{bmatrix} \alpha \\ \beta \end{bmatrix} \quad \mathbf{Y} = \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_T \end{bmatrix} \quad \mathbf{X} = \begin{bmatrix} 1 & X_1 \\ 1 & X_2 \\ \vdots & \vdots \\ 1 & X_T \end{bmatrix} \quad \mathbf{e} = \begin{bmatrix} e_1 \\ e_2 \\ \vdots \\ e_T \end{bmatrix}$$

(b) 令  $A = (X^T X)$  有

$$A = (X^T X) = \begin{bmatrix} T & \sum_{i=1}^T X_i \\ \sum_{i=1}^T X_i & \sum_{i=1}^T X_i^2 \end{bmatrix}$$

由 Gramer 法则

$$A^{-1} = \frac{A^*}{|A|} = \frac{\begin{bmatrix} \sum_{i=1}^T X_i^2 & -\sum_{i=1}^T X_i \\ -\sum_{i=1}^T X_i & T \end{bmatrix}}{|A|}$$

其中  $|A| = T \sum_{i=1}^T X_i^2 - (\sum_{i=1}^T X_i)^2$ , 从而得:

$$\hat{\boldsymbol{\theta}} = \begin{bmatrix} \hat{\alpha} \\ \hat{\beta} \end{bmatrix} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$$

$$= \frac{1}{|A|} \begin{bmatrix} \sum_{i=1}^T X_i^2 & -\sum_{i=1}^T X_i \\ -\sum_{i=1}^T X_i & T \end{bmatrix} \begin{bmatrix} 1 & \cdots & 1 \\ X_1 & \cdots & X_T \end{bmatrix} \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_T \end{bmatrix}$$

$$= \begin{bmatrix} \frac{(\frac{1}{T} \sum_{j=1}^T Y_j)(\frac{1}{T} \sum_{i=1}^T X_i^2) - (\frac{1}{T} \sum_{j=1}^T Y_j X_j)(\frac{1}{T} \sum_{i=1}^T X_i)}{\frac{1}{T} \sum_{i=1}^T X_i^2 - (\frac{1}{T} \sum_{i=1}^T X_i)^2} \\ \frac{(\frac{1}{T} \sum_{j=1}^T X_j Y_j) - (\frac{1}{T} \sum_{j=1}^T Y_j)(\frac{1}{T} \sum_{i=1}^T X_i)}{\frac{1}{T} \sum_{i=1}^T X_i^2 - (\frac{1}{T} \sum_{i=1}^T X_i)^2} \end{bmatrix} = \begin{bmatrix} \frac{1}{T} \sum_{j=1}^T Y_j - \frac{1}{T} \sum_{i=1}^T X_i \frac{(\frac{1}{T} \sum_{j=1}^T X_j Y_j) - (\frac{1}{T} \sum_{j=1}^T Y_j)(\frac{1}{T} \sum_{i=1}^T X_i)}{\frac{1}{T} \sum_{i=1}^T X_i^2 - (\frac{1}{T} \sum_{i=1}^T X_i)^2} \\ \frac{(\frac{1}{T} \sum_{j=1}^T X_j Y_j) - (\frac{1}{T} \sum_{j=1}^T Y_j)(\frac{1}{T} \sum_{i=1}^T X_i)}{\frac{1}{T} \sum_{i=1}^T X_i^2 - (\frac{1}{T} \sum_{i=1}^T X_i)^2} \end{bmatrix}$$

(c)

$$\mathbb{E}[Y_t] = \alpha + \beta\mathbb{E}[X_t] \quad \mathbb{E}[X_t Y_t] = \alpha\mathbb{E}[X_t] + \beta\mathbb{E}[X_t^2]$$

从而有

$$\beta = \frac{\mathbb{E}[X_t Y_t] - \mathbb{E}[X_t]\mathbb{E}[Y_t]}{\mathbb{E}[X_t^2] - \mathbb{E}[X_t]^2} = \frac{\text{cov}(X_t, Y_t)}{\text{var}X_t}$$

进而有

$$\alpha = \mathbb{E}[Y_t] - \mathbb{E}[X_t] \frac{\text{cov}(X_t, Y_t)}{\text{var}X_t}$$

又

$$\frac{1}{T} \sum_{i=1}^T X_i \xrightarrow{a.s.} \mathbb{E}X_t \quad \frac{1}{T} \sum_{i=1}^T Y_i \xrightarrow{a.s.} \mathbb{E}Y_t$$

$$\frac{1}{T} \sum_{i=1}^T X_i^2 - \left(\frac{1}{T} \sum_{i=1}^T X_i\right)^2 \xrightarrow{a.s.} \text{var}X_t$$

$$\left(\frac{1}{T} \sum_{j=1}^T X_j Y_j\right) - \left(\frac{1}{T} \sum_{j=1}^T Y_j\right) \left(\frac{1}{T} \sum_{i=1}^T X_i\right) \xrightarrow{a.s.} \text{cov}(X_t, Y_t)$$

所以

$$\hat{\boldsymbol{\theta}} = \begin{bmatrix} \hat{\alpha} \\ \hat{\beta} \end{bmatrix} \xrightarrow{a.s.} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \boldsymbol{\theta}$$

2. (a)

$$\begin{aligned} \mathbf{Y} &= \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_T \end{bmatrix} = \begin{bmatrix} \phi_1 X_0 + \phi_2 X_{1-2} + \cdots + \phi_p X_{1-p} \\ \phi_1 X_1 + \phi_2 X_0 + \cdots + \phi_p X_{2-p} \\ \vdots \\ \phi_1 X_{T-1} + \phi_2 X_{T-2} + \cdots + \phi_p X_{T-p} \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_T \end{bmatrix} \\ &= \begin{bmatrix} X_0 & \cdots & X_{1-p} \\ X_1 & \cdots & X_{2-p} \\ \vdots & \ddots & \vdots \\ X_{T-1} & \cdots & X_{T-p} \end{bmatrix} \begin{bmatrix} \phi_1 \\ \phi_2 \\ \vdots \\ \phi_p \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_T \end{bmatrix} \\ &= \mathbf{X}\boldsymbol{\phi} + \boldsymbol{\varepsilon} \end{aligned}$$

(b)

$$\begin{aligned} \frac{1}{T} \mathbf{X}^T \mathbf{X} &= \frac{1}{T} \begin{bmatrix} X_0 & \cdots & X_{T-1} \\ X_{1-2} & \cdots & X_{T-2} \\ \vdots & \ddots & \vdots \\ X_{1-p} & \cdots & X_{T-p} \end{bmatrix} \begin{bmatrix} X_0 & \cdots & X_{1-p} \\ X_1 & \cdots & X_{2-p} \\ \vdots & \ddots & \vdots \\ X_{T-1} & \cdots & X_{T-p} \end{bmatrix} \\ &= \frac{1}{T} \begin{bmatrix} \sum_{t=1}^T X_{t-1}^2 & \cdots & \sum_{t=1}^T (X_{t-1} X_{t-p}) \\ \sum_{t=1}^T (X_{t-2} X_{t-1}) & \cdots & \sum_{t=1}^T (X_{t-2} X_{t-p}) \\ \vdots & \ddots & \vdots \\ \sum_{t=1}^T (X_{t-p} X_{t-1}) & \cdots & \sum_{t=1}^T X_{t-p}^2 \end{bmatrix} \end{aligned}$$

因为

$$\frac{1}{T} \sum_{t=1}^T X_t X_{t-k} \xrightarrow{a.s.} \sigma(k)$$

所以

$$\frac{1}{T} \mathbf{X}^T \mathbf{X} \xrightarrow{a.s.} \begin{bmatrix} \sigma^2(0) & \cdots & \sigma^2(p-1) \\ \sigma^2(1) & \cdots & \sigma^2(p-2) \\ \vdots & \ddots & \vdots \\ \sigma^2(p-1) & \cdots & \sigma^2(0) \end{bmatrix}$$

(c) OLS 估计量为

$$\hat{\phi} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$$

有

$$\mathbf{X}^T \mathbf{Y} = \begin{bmatrix} X_0 & \cdots & X_{T-1} \\ X_{1-2} & \cdots & X_{T-2} \\ \vdots & \ddots & \vdots \\ X_{1-p} & \cdots & X_{T-p} \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_T \end{bmatrix} = \begin{bmatrix} \sum_{t=1}^T X_{t-1} X_t \\ \sum_{t=1}^T X_{t-2} X_t \\ \vdots \\ \sum_{t=1}^T X_{t-p} X_t \end{bmatrix} \xrightarrow{a.s.} T \begin{bmatrix} \sigma^2(1) \\ \sigma^2(2) \\ \vdots \\ \sigma^2(p) \end{bmatrix}$$

综合 (b) 结论

$$\left( \frac{1}{T} \mathbf{X}^T \mathbf{X} \right)^{-1} \left( \frac{1}{T} \mathbf{X}^T \mathbf{Y} \right) \xrightarrow{a.s.} \begin{bmatrix} \sigma^2(0) & \cdots & \sigma^2(p-1) \\ \sigma^2(1) & \cdots & \sigma^2(p-2) \\ \vdots & \ddots & \vdots \\ \sigma^2(p-1) & \cdots & \sigma^2(0) \end{bmatrix}^{-1} \begin{bmatrix} \sigma^2(1) \\ \sigma^2(2) \\ \vdots \\ \sigma^2(p) \end{bmatrix} = \begin{bmatrix} \phi_1 \\ \phi_2 \\ \vdots \\ \phi_p \end{bmatrix}$$

即

$$\hat{\phi} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y} \xrightarrow{a.s.} \phi$$

$\phi$  的 OLS 估计与 Yule-Walker 估计量一致